Error of Asymptotic Formulae for Volume Approximation of Convex Bodies in \mathbb{E}^3

Peter M. Gruber

Abstract. In this article the error of the asymptotic formula for volume approximation of sufficiently differentiable convex bodies in \mathbb{E}^3 by circumscribed convex polytopes is estimated. This then is applied to the isoperimetric problem for convex polytopes in a Minkowski 3-space.

MSC 2000. 52A15, 52A21, 52A27, 52A40, 52B11, 52B60.

Dedicated to Professor Sergej S. Ryškov on the occasion of his 70th birthday.

1 Introduction and Statement of Results

1.1 Let *C* be a *convex body* in Euclidean *d*-space \mathbb{E}^d , that is a compact convex subset of \mathbb{E}^d with non-empty interior and let δ^V be the symmetric difference metric on the space of all convex bodies in \mathbb{E}^d . For $n = d + 1, d + 2, \cdots$, denote by $\mathcal{P}_{(n)}^c$ the family of all convex polytopes in \mathbb{E}^d circumscribed to *C* which have at most *n* facets. Major approximation problems are to determine the quantity

$$\delta^V(C, \mathcal{P}^c_{(n)}) = \inf\{\delta^V(C, P) : P \in \mathcal{P}^c_{(n)}\}\$$

and to describe the polytopes for which equality holds, the *best approximating* polytopes of C in $\mathcal{P}_{(n)}^c$. Disregarding trivial cases, precise solutions of these problems are out of reach. General upper estimates for $\delta^V(C, \mathcal{P}_{(n)}^c)$ are easy to obtain. It is more difficult to determine the precise asymptotics of $\delta^V(C, \mathcal{P}_{(n)}^c)$ as $n \to \infty$. In [6, 8] it was shown that for C (the boundary of which is a surface) of class C^2 with Gauss curvature $\kappa_C > 0$ holds:

(1)
$$\delta^{V}(C, \mathcal{P}_{(n)}^{c}) \sim \frac{1}{2 n^{\frac{2}{d-1}}} \operatorname{div}_{d-1} A(C)^{\frac{d+1}{d-1}} \text{ as } n \to \infty.$$

Here A(C) is the equi-affine surface area measure of (the boundary of) C,

(2)
$$A(C) = \int_{\operatorname{bd} C} \kappa_C(x)^{\frac{1}{d+1}} d\sigma(x),$$

where σ is the ordinary surface area measure in \mathbb{E}^d . div_{d-1} is a constant depending on d. The only explicitly known values are div₁ = 1/12 and div₂ = 5/18 $\sqrt{3}$. The case d = 2 was settled before by Fejes Tóth [4]. For more information on the

voluminous literature on approximation of convex bodies by polytopes see the surveys [7, 9].

It is plausible to conjecture that for sufficiently differentiable C the formula (1) extends to an asymptotic series. For d = 2 the first two terms of this series were given by Ludwig [14] using tools from equi-affine differential geometry. The complete series was specified by Tabachnikov [18] in the form of a result on periodic trajectories of the dual billiard determined by C. For general d Böröczky [2] showed for convex bodies C of class C^3 with $\kappa_C > 0$ the formula

$$\delta^{V}(C, \mathcal{P}_{(n)}^{c}) = \frac{1}{2 n^{\frac{2}{d-1}}} \operatorname{div}_{d-1} A(C)^{\frac{d+1}{d-1}} + O\left(\frac{1}{n^{\frac{2}{d-1} + \frac{1}{8d^{2}}}}\right) \text{ as } n \to \infty.$$

1.2 The aim of this article is to prove the following result for d = 3.

Theorem. Let C be a convex body in \mathbb{E}^3 of class \mathcal{C}^3 with Gauss curvature $\kappa_C > 0$ and affine surface area A(C). Then

$$\delta^{V}(C, \mathcal{P}_{(n)}^{c}) = \frac{5A(C)^{2}}{36\sqrt{3}n} + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \ as \ n \to \infty.$$

Actually, a slightly stronger result will be given, see (3) and (41). A scrutiny of the proof shows that, as in [2], it is sufficient to assume that $\operatorname{bd} C$ has a representation of class \mathcal{C}^2 with Lipschitz second derivatives. The proof of our result makes use of geometric tools which, so far, are available only for d = 3.

Böröczky [3] informs us that in case C is a Euclidean ball in \mathbb{E}^3 , the error term in the asymptotic formula in the Theorem has a lower bound of the form

$$\frac{f(n)}{n^2}$$
, where $f(n) \to \infty$ as $n \to \infty$.

As remarked before, we conjecture that for sufficiently differentiable C, the asymptotic formula for $\delta^V(C, \mathcal{P}_{(n)}^c)$ can be extended to an asymptotic series. By the remark of Böröczky we see that the second term in this series is not of the form $B(C)/n^2$, as might be expected. Possibly, it has the form $C(C)/n^{3/2}$. Here B(C) and C(C) are suitable quantities depending on C.

Considering the recent contributions to asymptotic approximation of convex bodies by polytopes, it is clear that results similar to our Theorem and with similar proofs hold for the mean width deviation and for L^p metrics and also for families of inscribed and general polytopes and for vertices instead of facets. In some of these cases the proofs are technically more complicated.

For a corresponding, yet weaker result for general d see [12].

1.3 The Theorem can be applied to the isoperimetric problem for convex polytopes in a normed space: consider besides the Euclidean norm a further norm on \mathbb{E}^d . A natural choice for "volume" in the normed space thus obtained is the ordinary volume V. For "surface area" several natural definitions have been proposed. These amount to the introduction of a convex body I with center at the origin o, the so-called *isoperimetrix*. The surface area $S_I(C)$ of a convex body C then is defined by

$$S_I(C) = \lim_{\varepsilon \to +0} \frac{V(C + \varepsilon I) - V(C)}{\varepsilon}, \text{ where } C + \varepsilon I = \{x + \varepsilon y : x \in C, y \in I\},\$$

see Thompson [18]. If P is a convex polytope with minimum *isoperimetric quo*tient $S_I(C)^d/V(C)^{d-1}$ amongst those with a given number of facets, a result of Diskant [5] says that after applying a suitable homothety to P, we may assume that P is circumscribed to I. The definition of $S_I(P)$ then shows that

$$\frac{S_I(P)^d}{V(P)^{d-1}} = d^d V(P) = d^d V(I) + d^d \delta^V(I, P).$$

The asymptotic formula (1) and its refinements thus yield asymptotic formulae for the minimum isoperimetric quotient. In particular, our Theorem implies the following result.

Corollary. Let I be an isoperimetrix in \mathbb{E}^3 of class \mathcal{C}^3 with $\kappa_C > 0$ and affine surface area A(C) which corresponds to a given norm on \mathbb{E}^3 . For $n = 4, 5, \ldots$, let P_n be a convex polytope in \mathbb{E}^3 with minimum isoperimetric quotient $S_I(P_n)^3/V(P_n)^2$ amongst all convex polytopes in \mathbb{E}^3 with n facets. Assume (without restriction of generality) that P_n is circumscribed to I. Then

$$\frac{S_I(P_n)^3}{V(P_n)^2} = 27V(I) + \frac{5\sqrt{3}A(I)^2}{4n} + O\Big(\frac{1}{n^{1+\frac{1}{4}}}\Big) \ as \ n \to \infty.$$

1.4 In [11] we gave an asymptotic formula for the maximum error in numerical integration formulas for certain classes of continuous functions on the plane or on Riemannian 2-manifolds. Using ideas of the proof of our Theorem, it is possible to estimate the error of this asymptotic formula.

2 Proof of the Theorem

Let \sharp , diam, width, $|\cdot|$, $V(\cdot)$, bd, int, relbd, relint, vert and conv stand for cardinal number, diameter and minimum width (both with respect to the Euclidean norm $\|\cdot\|$ in \mathbb{E}^3), ordinary area (2-dimensional Hausdorff measure) and volume, boundary, interior, relative boundary and interior, set of vertices and convex hull, respectively. It will always be clear from the context with respect to which set relbd and relint are considered. B^2 and S^2 denote the solid Euclidean unit circle and the Euclidean 2-sphere. For notions not explained below see Schneider [16].

When writing const or α, β, \ldots , we mean that this is a suitable positive constant depending only on C. Landau symbols such as O(1/m) denote functions of the form const/m (in slight contrast to the use in section 1). Constants and Landau symbols may be different, even if they are denoted alike.

2.1 Lower Estimate. We shall prove that

(3)
$$\delta^{V}(C, \mathcal{P}_{(n)}^{c}) \ge \frac{5A(C)^{2}}{36\sqrt{3}n} - O\left(\frac{1}{n^{1+\frac{1}{2}}}\right) \text{ as } n \to \infty.$$

For $n = 4, 5, \ldots$, let $P_n \in \mathcal{P}_{(n)}^c$ be best approximating for C.

2.1.1 First, some tools will be collected. A result of the author [10] says that " P_n has asymptotically regular hexagonal facets of edge length $(A(C)/3^{3/2} n)^{1/2}$ with respect to the Riemannian metric of equi-affine differential geometry on bd C". Noting that two Riemannian metrics on the compact manifold bd C are metrically equivalent, this implies in particular that

(4) there is a facet F_0 of P_n with diam $F_0 \leq O(1/n^{1/2})$ and the point where F_0 touches C has distance at most $O(1/n^{1/2})$ from the points where the adjacent facets touch C.

The metric projection " π " of \mathbb{E}^3 onto C maps each point in \mathbb{E}^3 onto its (unique) nearest point in C. The rolling theorem of Blaschke [1], pp.118 and 119, see also Leichtweiss [13], p.1055, and its dual yield the following remarks:

- (5) For any $p \in \operatorname{bd} C$ and r on the support plane H_p of C at p with $||p-r|| \le \alpha$ holds $\beta ||p-r||^2 \le ||r-r^{\pi}|| \le \gamma ||p-r||^2$.
- (6) For any $r \in \mathbb{E}^3 \setminus C$ with $||r r^{\pi}|| \leq \text{const}$ the volume of the convex cone with apex r and base $H_{r^{\pi}} \cap \text{conv}(\{r\} \cup C)$ is at least $\delta ||r r^{\pi}||^2$.

Next, we state some well-known properties of π :

(7)
$$||x^{\pi} - y^{\pi}|| \le ||x - y||$$
 for $x, y \in \mathbb{E}^3$.

- (8) Let $z \in \operatorname{bd} C$. Then $\{y \in \mathbb{E}^3 : y^{\pi} = z\}$ is the exterior normal of $\operatorname{bd} C$ at z.
- (9) $|S^{\pi}| \leq |S|$ for any measurable piece S of a surface.
- (10) Let Q be a convex polytope containing C. Then π maps $\operatorname{bd} Q$ homeomorphically onto $\operatorname{bd} C$.

Further needed tools are the following standard representation of $\operatorname{bd} C$ and some of its properties. For $p \in \operatorname{bd} C$ choose in the support plane H_p of C at p a Cartesian coordinate system with origin o equal to p. Together with the interior normal unit vector of $\operatorname{bd} C$ at p it yields a Cartesian coordinate system of \mathbb{E}^3 . When speaking of the "lower" part of $\operatorname{bd} C$, this is meant with respect to the last coordinate. Let $\varepsilon > 0$ be so small that the ε -neighborhood U_p of p in $\operatorname{bd} C$ is in the relative interior of the lower part of $\operatorname{bd} C$. Represent U_p in the form

(11)
$$U_p = \{(s, f_p(s)) : s \in U'_p\},\$$

where "'" denotes the orthogonal projection of \mathbb{E}^3 onto H_p and f_p is a convex function of class \mathcal{C}^3 on the relatively open set U'_p . The next proposition is a slight extension of a result of Schneider [15] and can be proved along the same lines.

(12)
$$f_p$$
 is convex, of class \mathcal{C}^3 , and
 $|f_{p,k}|, |f_{p,kl}|, |f_{p,klm}|, (\operatorname{grad} f_p)^2 \leq \operatorname{const}$ on U_p ,

where $f_{p,k}, f_{p,kl}, f_{p,klm}$ denote first, second and third partial derivatives of f_p . Define quadratic forms q_u on \mathbb{E}^2 by

$$q_u(s) = \sum_{k,l} f_{p,kl}(u) s^k s^l$$
 for $u \in U'_p$ and $s = (s^1, s^2) \in I\!\!E^2$.

Instead of q_u , where u = p' = p, we also write q_p . As a consequence of *Blaschke's* rolling theorem and its dual we have the inequalities

(13) $\operatorname{const} \| \cdot \|^2 \le q_p(\cdot) \le \operatorname{const} \| \cdot \|^2.$

For $x \in U_p$ we write instead of $\kappa_C(x)$ also $\kappa_C(u)$ where u = x'. Using the common expression for κ_C ,

$$\kappa_C(u) = \frac{\det q_u}{(1 + (\operatorname{grad} f_p(u))^2)^2} \text{ for } u \in U'_p,$$

and noting (12), it follows that

(14)
$$\kappa_C(o) = \det q_p$$
 and
 κ_C is of class \mathcal{C}^1 and has bounded first partial derivatives on U'_n .

Let D be a convex disc, that is a convex body in \mathbb{E}^2 . Its moment M(D, o) with respect to the origin o is defined by

$$M(D,o) = \int_{D} \|s\|^2 \, ds$$

A related function M(a, v) is defined as follows:

$$M(a,v) = \frac{a^2}{2v\tan^2\frac{\pi}{v}} \int_0^{\frac{\pi}{v}} \frac{d\varphi}{\cos^4\varphi} \text{ for } a > 0, v \ge 3.$$

If v is an integer, M(a, v) is the moment of a regular convex v-gon with center o and area a. Elementary calculations yield the following properties:

(15) Let D be a convex disc in \mathbb{E}^2 . Then $M(tD, o) = t^4 M(D, o)$ for $t \ge 0$.

(16) Let D be a convex disc in \mathbb{E}^2 and $q(s) = s^{\text{tr}} A^{\text{tr}} A s$ for $s \in \mathbb{E}^2$ a positive definite quadratic form, where A is a suitable 2×2 matrix. Then

$$\int_D q(s) \, ds = M(AD, o) \, (\det q)^{-\frac{1}{2}}.$$

(17) Let *H* be a convex hexagon with center *o* which is regular with respect to the norm $q^{\frac{1}{2}}$, where *q* is a positive definite quadratic form on \mathbb{E}^2 . Then

$$M(H,o) = \frac{5|H|^2(\det q)^{\frac{1}{2}}}{18\sqrt{3}}$$

The moment lemma of Fejes Tóth [4], p.198, says the following:

(18) Let D be a convex v-gon and E a regular convex v-gon with center o and |D| = |E|. Then $M(D, o) \ge M(E, o) = M(|E|, v)$.

The next two results are due to the author [10]:

- (19) M(a, v) is convex in (a, v) for $a > 0, v \ge 3$.
- (20) M(a, v) is non-increasing in v for any fixed a > 0.

The final tool is a corollary of *Euler's polytope formula*, see e.g. Fejes Tóth [4], p.15:

(21) Let P be a convex polytope in \mathbb{E}^3 with n facets and let v_1, \ldots, v_n be the number of the vertices of its facets. Then

$$\frac{1}{n}(v_1 + \dots + v_n) < 6.$$

2.1.2 Second, we consider the form of the facets of best approximating polytopes P_n . Our first aim is to show that

(22) max {diam F : F facet of P_n } $\leq O\left(\frac{1}{n^{\frac{1}{2}}}\right)$.

For the proof of (22) note that the following weaker estimate is an immediate consequence of the fact that $\delta^V(C, P_n) \to 0$.

(23) max {diam F : F facet of P_n } $\rightarrow 0$.

This implies that for all sufficiently large n the intersection of the support halfspaces of P_n , except the facet F_0 (see (4)), is a convex polytope $Q_{n-1} \in \mathcal{P}_{(n-1)}^c$, say, and $Q_{n-1} \setminus P_n$ is a convex polytope with facet F_0 which is situated "above" F_0 . It follows from (4) that $|F_0| \leq O(1/n)$ and (4) together with (5) implies that the maximum "height" of $Q_{n-1} \setminus P_n$ above F_0 is at most O(1/n). Thus

(24)
$$Q_{n-1} \in \mathcal{P}_{(n-1)}^c, \ V(Q_{n-1}) - V(P_n) \le O\left(\frac{1}{n}\right)O\left(\frac{1}{n}\right) = \frac{\zeta}{n^2},$$

say. In order to prove (22), assume the contrary. Choose

(25)
$$\eta > \left(\frac{\zeta}{\beta^2 \delta}\right)^{\frac{1}{4}}.$$

Then there are infinitely many n (and from now on only these n will be considered in the proof of (22)) with the following property: P_n has a facet G_0 , say, such that diam $G_0 \ge 2\eta/n^{1/2}$. Thus G_0 has a vertex r, say, such that $\|p-r\| \ge \eta/n^{1/2}$, where p is the point where G_0 touches C. By (23) we see that $\|p-r\| \le \alpha$ for sufficiently large n where α is from (5). Hence (5) implies that $\|r-r^{\pi}\| \ge \beta \|p-r\|^2 \ge \beta \eta^2/n$. On the other hand, $\delta^V(C, P_n) \to 0$ and (24) together show that $\delta^V(C, Q_{n-1}) \to 0$, which, in turn, yields that $\|r-r^{\pi}\| \to 0$ as $n \to \infty$. Let R_n be the intersection of Q_{n-1} and the support halfspace of C at r^{π} . Then $\|r-r^{\pi}\| \to 0$, $\|r-r^{\pi}\| \ge \beta \eta^2/n$ and propositions (6) and (25) together imply that for sufficiently large n,

$$R_n \in \mathcal{P}_{(n)}^c, V(Q_{n-1}) - V(R_n) \ge \delta \|r - r^{\pi}\|^2 \ge \frac{\beta^2 \,\delta \,\eta^4}{n^2} > \frac{\zeta}{n^2}$$

Considering this and (24), we see that for sufficiently large n holds

$$R_n \in \mathcal{P}_{(n)}^c, V(R_n) < V(P_n) - \frac{\zeta}{n^2} + \frac{\zeta}{n^2} = V(P_n)$$

Since this contradicts the fact that P_n is best approximating for C in $\mathcal{P}_{(n)}^c$, the proof of (22) is complete.

A similar proof shows that

(26) min {width
$$F : F$$
 facet of P_n } $\geq O\left(\frac{1}{n^{\frac{1}{2}}}\right)$.

2.1.3 Third, we adapt the standard representation of $\operatorname{bd} C$ as described in 2.1.1 according to our needs.

Let $F_i, i = 1, ..., n$, denote the facets of P_n and let p_i be the point where F_i touches C. For each p_i choose corresponding H_i , Cartesian coordinate systems for H_i , resp. $\mathbb{I}\!\!E^3$ with origin o equal to p_i , and U_i, f_i, q_i and "'". Propositions (26) and (22) together with $o \in F_i$ imply that

(27)
$$c_i + \frac{\vartheta}{n^{\frac{1}{2}}} B^2 \subseteq F_i \subseteq \frac{\iota}{n^{\frac{1}{2}}} B^2$$
 for suitable $c_i \in H_i$.

In the following we consider only n which are so large that

$$(28) \quad F_i \subset U'_i.$$

(Note (22) and the fact that U_i is the ε -neighborhood of p_i in bd C, where $\varepsilon > 0$ is a constant.) Propositions (11)–(14) now take the following form:

- (29) $U_i = \{(s, f_i(s)) : s \in U'_i\}.$
- (30) f_i is convex, of class \mathcal{C}^3 , and $|f_{i,k}|, |f_{i,kl}|, |f_{i,klm}|, (\operatorname{grad} f_i)^2 \leq \operatorname{const} \operatorname{on} U'_i.$
- (31) $\operatorname{const} \| \cdot \|^2 \le q_i(\cdot) \le \operatorname{const} \| \cdot \|^2.$
- (32) $\kappa_C(o) = \det q_i, \kappa_C \text{ is of class } \mathcal{C}^1, \text{ and}$ has bounded first partial derivatives on U'_i .

Represent q_i in the form

(33) $q_i(s) = s^{\text{tr}} A_i^{\text{tr}} A_i s$ for $s \in \mathbb{E}^2$, where A_i is a suitable 2×2 matrix.

Since $f_i(o) = 0$ and $\operatorname{grad} f_i(o) = o$, Taylor's theorem together with (28)–(31) implies that

(34)
$$f_i(s) \ge \frac{1}{2}q_i(s) - O(q_i(s)^{\frac{3}{2}}) \text{ for } s \in F_i \subseteq U'_i \subseteq H_i.$$

Since $p_i = o \in F_i \cap C$ and $F_i \subseteq (\iota/n^{1/2})B^2$ by (27), proposition (7) shows that $F_i^{\pi} \subseteq (\iota/n^{1/2})B^3$ and thus

$$(35) \quad F_i^{\pi\prime} \subset \frac{\iota}{n^{\frac{1}{2}}} B^2.$$

Some elementary calculations together with $f_i(o) = 0$, $\operatorname{grad} f_i(o) = o$, Taylor's theorem and propositions (27), (35), (28) and (30) imply the inequality

(36)
$$||x - x^{\pi'}|| < \frac{\kappa}{n^{\frac{3}{2}}} \text{ for } x \in F_i.$$

2.1.4 Fourth, we consider a dissection of $\operatorname{bd} C$. By (7) and (10) the metric projection π is non-increasing for curve length and maps $\operatorname{bd} P_n$ homeomorphically onto $\operatorname{bd} C$. Thus

(37) the sets
$$F_i^{\pi}$$
, $i = 1, ..., n$, form a dissection of bd C.

This means that the sets are closed, their boundaries are continuous curves of finite length, they have pairwise disjoint interiors and their union equals $\operatorname{bd} C$. Let

(38)
$$P_{ni} = \{(s,t) \in P_n : s \in (1 - \frac{\kappa}{\vartheta n})(F_i - c_i) + c_i, \ 0 \le t \le f_i(s)\} \subseteq P_n \setminus \operatorname{int} C$$

(compare (27)). Next it will be shown that

(39) the sets P_{ni} , i = 1, ..., n, are pairwise disjoint subsets of $P_n \setminus \text{int } C$.

By (37) it is sufficient for the proof of (39) to show that

(40)
$$P_{ni}^{\pi} \subset \operatorname{relint} F_i^{\pi}.$$

Being a continuous image of the connected set P_{ni} , the set P_{ni}^{π} is also connected. F_i^{π} and P_{ni}^{π} have a common relative interior point, namely p_i , and both are contained in bd C. Thus, if (40) did not hold, $P_{ni}^{\pi} \cap \text{relbd} F_i^{\pi} \neq \emptyset$. Then there is a point $y \in P_{ni}$ such that $y^{\pi} \in \text{relbd} F_i^{\pi}$. Choose $x \in \text{relbd} F_i$ with $x^{\pi} = y^{\pi}$. It follows from (8) that $y \in [x, x^{\pi}]$. Hence $||x - y'|| \leq ||x - x^{\pi'}|| < \kappa/n^{3/2}$ by (36). This together with $y = (s, t) \in P_{ni}, s = y'$, (38) and (27) implies that

$$x = y' + x - y' \in (1 - \frac{\kappa}{\vartheta n})(F_i - c_i) + c_i + \frac{\kappa}{n^{\frac{3}{2}}} \operatorname{relint} B^2$$
$$\subseteq (1 - \frac{\kappa}{\vartheta n})(F_i - c_i) + c_i + \frac{\kappa}{\vartheta n}(\operatorname{relint} F_i - c_i) \subseteq \operatorname{relint} F_i.$$

Since this contradicts the fact that $x \in \operatorname{relbd} F_i$, the proof of (40) is complete which, in turn, yields (39).

2.1.5 Finally, the fact that P_n is best approximating, (39), (38) where we put $(1 - \kappa/\vartheta n)(F_i - c_i) + c_i = (1 - O(1/n))F_i + d_i$, say, (34), (31), (27), (33), (16), (15), (18) where $v_i = \sharp$ vert F_i , det $A_i = (\det q_i)^{1/2}$ and (15), (32), (9), (20), a calculus formula for surface area, (32), (35), (15), a calculus formula for surface integrals, (19), Jensen's inequality, (37), (2), (20), (21) and (17) together imply proposition (3):

$$\begin{split} \delta^{V}(C,\mathcal{P}_{(n)}^{c}) &= \delta^{V}(C,P_{n}) = V(P_{n} \setminus \operatorname{int} C) \geq \sum_{i} V(P_{ni}) \\ &= \sum_{i} \int_{(1-O(\frac{1}{n}))F_{i}+d_{i}} f_{i}(s) \, ds \geq \frac{1}{2} \sum_{i} \int_{(1-O(\frac{1}{n}))F_{i}+d_{i}} q_{i}(s) \, ds \, (1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &= \frac{1}{2} \sum_{i} M((1-O(\frac{1}{n}))A_{i}F_{i} + A_{i}d_{i}, o)(\det q_{i})^{-\frac{1}{2}}(1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &\geq \frac{1}{2} \sum_{i} M(|A_{i}F_{i}|, v_{i})(\det q_{i})^{-\frac{1}{2}}(1-O(\frac{1}{n}))^{4}(1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &\geq \frac{1}{2} \sum_{i} M((\det q_{i})^{\frac{1}{4}}|F_{i}|, v_{i})(1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &\geq \frac{1}{2} \sum_{i} M(\kappa_{C}(o)^{\frac{1}{4}}|F_{i}^{\pi}|, v_{i})(1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &\geq \frac{1}{2} \sum_{i} M(\int_{F_{i}^{\pi'}} \kappa_{C}(o)^{\frac{1}{4}}(1+(\operatorname{grad} f_{i}(s))^{2})^{\frac{1}{2}} \, ds, \, v_{i}) \, (1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &\geq \frac{1}{2} \sum_{i} M(\int_{F_{i}^{\pi'}} \kappa_{C}(s)^{\frac{1}{4}}(1+(\operatorname{grad} f_{i}(s))^{2})^{\frac{1}{2}} \, ds \, (1-O(\frac{1}{n^{\frac{1}{2}}})), v_{i}) \\ &\qquad \times (1-O(\frac{1}{n^{\frac{1}{2}}})) \\ &= \frac{1}{2} \sum_{i} M(\int_{F_{i}^{\pi'}} \kappa_{C}(x)^{\frac{1}{4}} \, d\sigma(x), v_{i})(1-O(\frac{1}{n^{\frac{1}{2}}}))^{4}(1-O(\frac{1}{n^{\frac{1}{2}}})) \end{split}$$

$$\geq \frac{n}{2}M(\frac{1}{n}\int_{\mathrm{bd}\,C}\kappa_C(x)^{\frac{1}{4}}\,d\sigma(x),\frac{1}{n}(v_1+\cdots+v_n))(1-O\left(\frac{1}{n^{\frac{1}{2}}}\right))\\\geq \frac{n}{2}M(\frac{1}{n}A(C),6)\,(1-O\left(\frac{1}{n^{\frac{1}{2}}}\right)) = \frac{5A(C)^2}{36\sqrt{3}\,n} - O\left(\frac{1}{n^{1+\frac{1}{2}}}\right).$$

2.2 Upper Estimate. We shall prove that

(41)
$$\delta^{V}(C, \mathcal{P}_{(n)}^{c}) \leq \frac{5A(C)^{2}}{36\sqrt{3}n} + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \text{ as } n \to \infty.$$

2.2.1 First, a suitable representation of $\operatorname{bd} C$ will be introduced, different from the one in 2.1.

For a proof of the following result for general d see [12].

(42) For m = 1, 2, ..., the 2-sphere S^2 can be dissected into m convex spherical polygons $S_i, i = 1, ..., m$, say, such that for each i a circle of radius $O(1/m^{1/2})$ is contained in S_i and S_i is contained in a concentric circle of radius $O(1/m^{1/2})$.

Assume that $o \in \operatorname{int} C$. Then for each $m = 1, 2, \ldots$, dissect $\operatorname{bd} C$ as follows: project the convex spherical polygons $S_i \subset S^2$ in radial direction onto $\operatorname{bd} C$. This gives a dissection of $\operatorname{bd} C$ into m sets $C_i, i = 1, \ldots, m$, say. For each iconsider the ray starting at o which meets S_i at the center of the two circles corresponding to S_i according to (42). Let H_i be a plane which intersects this ray orthogonally, but does not meet C. Let "'" denote the orthogonal projection onto H_i . Choose a Cartesian coordinate system in H_i with origin o at the point where the corresponding ray intersects H_i . Then, for sufficiently large m,

(43) the *m* sets C_i , i = 1, ..., m, form a dissection of bd *C*, each C_i is a convex disc in H_i , and

$$\frac{\lambda}{m^{\frac{1}{2}}}B^2 \subseteq C'_i \subseteq \frac{\mu}{m^{\frac{1}{2}}}B^2.$$

The Cartesian coordinate system in H_i together with the normal unit vector of H_i which points to C forms a Cartesian coordinate system of \mathbb{E}^3 . When we speak of the "lower" part of bd C, this is with respect to the last coordinate. Represent the lower part of bd C in the form

 $(44) \quad \{(s, f_i(s)) : s \in C'\}.$

Then, if m is sufficiently large, an argument of Schneider [15] shows (as in 2.1) that

(45) f_i is convex, of class \mathcal{C}^3 , and $|f_{i,k}|, |f_{i,kl}|, |f_{i,klm}|, (\operatorname{grad} f_i)^2 \leq \operatorname{const} \operatorname{on} \frac{2\mu}{m^{\frac{1}{2}}} B^2.$

Define quadratic forms q_u by

(46)
$$q_u(s) = \sum_{k,l} f_{i,kl}(u) s^k s^l \text{ for } s \in \mathbb{E}^3, \text{ where } u \in \frac{2\mu}{m^{\frac{1}{2}}} B^2,$$

 $q_i = q_o.$

As a consequence of Blaschke's rolling theorem and the fact that the coefficient of q_u are continuous in u we have for sufficiently large m that

(47)
$$\nu \| \cdot \|^2 \le q_i(\cdot) \le \xi \| \cdot \|^2$$
,

(48)
$$q_u \leq 2q_i \text{ for any } u \in \frac{2\mu}{m^{\frac{1}{2}}}B^2.$$

Finally, we note that for sufficiently large m,

(49)
$$\kappa_C(u) = \frac{\det q_u}{(1 + (\operatorname{grad} f_i(u))^2)^2} \text{ for } u \in \frac{2\mu}{m^{\frac{1}{2}}} B^2.$$

2.2.2 Second, we shall construct "almost" best approximating polytopes Q_n for C in $\mathcal{P}_{(n)}^c$. Let n be sufficiently large and let $m = \lfloor n^{1/2} \rfloor$. Consider in H_i an edge-to-edge tiling with convex hexagons of area $|C'_i|A(C)/A(C_i)n$ which are regular with respect to the norm $q_i^{1/2}$. Here

(50)
$$A(C_i) = \int_{C_i} \kappa_C(x)^{\frac{1}{4}} d\sigma(x), A(C) = \int_{\operatorname{bd} C} \kappa_C(x)^{\frac{1}{4}} d\sigma(x).$$

Since $|C'_i| \leq |C_i| \leq \text{const} |C'_i|$ by (43) and (46) and since κ_C is continuous and positive on the compact surface $\operatorname{bd} C$, we see that $|C'_i|A(C)/A(C_i)$ is bounded between positive constants. This combined with (47) shows that the diameter of each of these hexagons is at most $\rho/n^{1/2}$. From (43) it follows that

$$(1 - \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}})C'_{i} + \frac{\rho}{n^{\frac{1}{2}}}B^{2} \subseteq (1 - \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}} + \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}})C'_{i} = C'_{i}.$$

Thus $D'_i = (1 - (\rho/\lambda)(m/n)^{1/2})C'_i$ is contained in relint C'_i and has distance at least $\rho/n^{1/2}$ from relbd C'_i . Consider the hexagons of our tiling which meet D'_i . Since each hexagon has diameter at most $\rho/n^{1/2}$, all these hexagons are contained in C'_i . Hence there are

(51)
$$n_i \le \frac{A(C_i)}{A(C)}n$$

such hexagons. Multiplying each of these hexagons with the factor

$$\frac{1+\frac{\rho}{\lambda}\left(\frac{m}{n}\right)^{\frac{1}{2}}}{1-\frac{\rho}{\lambda}\left(\frac{m}{n}\right)^{\frac{1}{2}}} \quad (\leq 1+O\left(\frac{1}{n^{\frac{1}{4}}}\right) \leq 2 \text{ for sufficiently large } n),$$

gives a system of n_i hexagons H_{ij} , $j = 1, ..., n_i$, in the plane H_i . For sufficiently large n this system of hexagons has the following properties:

(52)
$$\operatorname{diam} H_{ij} \le \frac{2\rho}{n^{\frac{1}{2}}},$$

(53)
$$|H_{ij}| \le \frac{|C_i'|A(C)(1+O\left(\frac{1}{n^{\frac{1}{4}}}\right))^2}{A(C_i)n} \le \frac{|C_i'|A(C)}{A(C_i)n}(1+O\left(\frac{1}{n^{\frac{1}{4}}}\right)) \le O\left(\frac{1}{n}\right),$$

(54)
$$H_{ij} \subset (1 + O\left(\frac{1}{n^{\frac{1}{4}}}\right))C'_i \subseteq 2C'_i \subseteq \frac{2\mu}{m^{\frac{1}{2}}}B^2 \subset C',$$

(55)
$$H_{i1} \cup \dots \cup H_{in_i} \supseteq \frac{1 + \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}}}{1 - \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}}} (1 - \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}}) C'_i$$
$$= C'_i + \frac{\rho}{\lambda} \left(\frac{m}{n}\right)^{\frac{1}{2}} C'_i \supseteq C'_i + \frac{\rho}{n^{\frac{1}{2}}} B^2 \supseteq C'_i.$$

This follows from the definition of these hexagons, the above remarks and propositions (43) and (50). Choose points p_{ij} on the lower side of bd C such that p'_{ij} is the center of H_{ij} and define corresponding quadratic forms q_{ij} by

(56)
$$q_{ij}(s) = q_{p'_{ij}}(s) = \sum_{k,l} f_{i,kl}(p'_{ij}) s^k s^l \text{ for } s \in I\!\!E^2.$$

Noticing (46), (48) and (54), we have that

$$(57) \quad q_{ij} \le 2q_i.$$

Finally, define Q_n to be the intersection of the support halfspaces of C at the points p_{ij} . (If n is sufficiently large, these points are distributed rather densely over bd C and thus) Q_n is a convex polytope with at most $n_1 + \cdots + n_m \leq n$ facets (see (51) and (43)) which is circumscribed to C. Hence

$$(58) \quad Q_n \in \mathcal{P}^c_{(n)}.$$

2.2.3 Third, we cover $Q_n \setminus \text{int } C$ by sets whose volume may be easily calculated. Since the sets C_i , $i = 1, \ldots, m$, form a dissection of bd C by (43), we have that

(59)
$$Q_n \setminus \operatorname{int} C \subset Q_{n1} \cup \cdots \cup Q_{nm}$$
, where $Q_{ni} = \{x \in Q_n \setminus \operatorname{int} C : x^{\pi} \in C_i\}$.

Next, the following will be shown:

(60)
$$Q_{ni} \subset R_{ni} = \{(s,t) \in Q_n : s \in C'_i + \frac{\rho}{n^{\frac{1}{2}}}B^2, t \leq f_i(s)\}$$
for sufficiently large n .

For the proof of (60) it is sufficient to show the following: let $x \in Q_n \setminus \operatorname{int} C$ with $x^{\pi} \in C_i$ be given, then $||x' - x^{\pi'}|| < \rho/n^{1/2}$. Since $x^{\pi} \in C_i$ and thus $x^{\pi'} \in C'_i$, proposition (55) implies that $x^{\pi'} \in H_{ij}$ for suitable j. Elementary calculations, Taylor's theorem, (52), (45), (47) and (48) together show that the distance of x^{π} from the intersection point y of the exterior normal of $\operatorname{bd} C$ at x^{π} with the support plane of C at p_{ij} is at most O(1/n). Since $x \in [x^{\pi}, y]$ by (8),

$$||x' - x^{\pi'}|| \le ||y' - x^{\pi'}|| \le ||y - x^{\pi}|| \le O\left(\frac{1}{n}\right).$$

Since $O(1/n) < \rho/n^{1/2}$ for sufficiently large n, the proof of (60) is complete.

2.2.4 Finally, (59), (60), (55), the definition of Q_{ni} , Taylor's theorem applied to $f_i|H_{ij}$, (56) and $||s - p'_{ij}|| \leq O(1/n^{1/2})$ (see (52)), (55) and (45), Taylor's theorem applied to the coefficients of q_i and the fact that $||p'_{ij} - o|| \leq O(1/m^{1/2})$ (see (54)) and $||s - p_{ij'}|| \leq O(1/n^{1/2})$ (see (52)), (17), (53), (51), (53), (50), (49), (46), Taylor's theorem applied to $\kappa_C(s)^{1/4}(1 + (\operatorname{grad} f_i(s))^2)^{1/2}|C'_i$ which has bounded partial derivatives by (45) combined with $||s - o|| \leq O(1/m^{1/2})$ (see (43)), a calculus formula for surface integrals, the definition of $A(C_i)$ and (43) together imply proposition (41):

$$\begin{split} \delta^{V}(C,Q_{n}) &= V(Q_{n} \setminus \operatorname{int} C) \leq \sum_{i} V(Q_{ni}) \leq \sum_{i} V(R_{ni}) \\ &\leq \sum_{i,j} \int_{H_{ij}} \{f_{i}(s) - f_{i}(p_{ij}') - \operatorname{grad} f_{i}(p_{ij}')(s - p_{ij}')\} \, ds \\ &\leq \frac{1}{2} \sum_{i,j} \int_{H_{ij}} q_{ij}(s - p_{ij}') \, ds + |H_{ij}| \, O\left(\frac{1}{n^{\frac{3}{2}}}\right)\} \\ &\leq \frac{1}{2} \sum_{i,j} \{\int_{H_{ij}} q_{i}(s - p_{ij}') \, ds + |H_{ij}| \, O\left(\frac{1}{n^{\frac{3}{2}}}\right) + |H_{ij}| \, O\left(\frac{1}{n \, m^{\frac{1}{2}}}\right)\} \\ &\leq \frac{1}{2} \sum_{i,j} n_{i} \frac{5 |H_{ij}|^{2} (\det q_{i})^{\frac{1}{2}}}{18\sqrt{3}} \left(1 + O\left(\frac{1}{n^{\frac{1}{4}}}\right)\right)^{4} + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \\ &\leq \frac{5}{36\sqrt{3}n} \sum_{i} A(C_{i})^{1-2} A(C)^{2-1} |C_{i}'|^{2} \kappa_{C}(o)^{\frac{1}{2}} (1 + (\operatorname{grad} f_{i}(o))^{2}) \\ &\times (1 + O\left(\frac{1}{n^{\frac{1}{4}}}\right)) + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \\ &= \frac{5A(C)}{36\sqrt{3}n} \sum_{i} A(C_{i})^{-1} (\int_{C_{i}'} \kappa_{C}(o)^{\frac{1}{4}} (1 + (\operatorname{grad} f_{i}(o))^{2})^{\frac{1}{2}} \, ds)^{2} \\ &\times (1 + O\left(\frac{1}{n^{\frac{1}{4}}}\right)) + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \\ &\leq \frac{5A(C)}{36\sqrt{3}n} \sum_{i} A(C_{i})^{-1} (\int_{C_{i}'} \kappa_{C}(s)^{\frac{1}{4}} (1 + (\operatorname{grad} f_{i}(s))^{2})^{\frac{1}{2}} \, ds)^{2} \\ &\times (1 + O\left(\frac{1}{m^{\frac{1}{2}}}\right))^{2} (1 + O\left(\frac{1}{n^{\frac{1}{4}}}\right)) + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \\ &= \frac{5A(C)}{36\sqrt{3}n} \sum_{i} A(C_{i}) (1 + O\left(\frac{1}{n^{\frac{1}{4}}}\right)) + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right) \\ &= \frac{5A(C)^{2}}{36\sqrt{3}n} + O\left(\frac{1}{n^{1+\frac{1}{4}}}\right). \end{split}$$

2.3 Conclusion. The Theorem now follows from (3) and (41).

3 Acknowledgement

I am obliged to Professors Goodey, Ludwig and Schnitzer for their advice and references to the literature.

References

- [1] Blaschke, W., Kreis und Kugel, 2nd ed., de Gruyter, Berlin 1956
- [2] Böröczky, K., Jr., The error of polytopal approximation with respect to the symmetric difference metric and the L_p metric, *Israel J. Math.*, in print
- [3] Böröczky, K., Jr., personal communication, 2000
- [4] Fejes Tóth,L., Lagerungen in der Ebene, auf der Kugel und im Raum, Springer-Verlag, Berlin 1953, 2nd ed., 1972
- [5] Diskant, V.I., Making precise the isoperimetric inequality and stability theorems in the theory of convex bodies, *Trudy Mat. Inst. Steklov.* 14 (1989) 98-132
- [6] Gruber, P.M., Volume approximation of convex bodies by circumscribed polytopes, DI-MACS Ser. Discrete Math. Theor. Computer Sci. 4 (1991) 309 – 317
- [7] Gruber, P.M., Aspects of approximation of convex bodies, in: P.M.Gruber, J.M.Wills, eds., Handbook of convex geometry, vol.A, 319 – 345, North-Holland, Amsterdam 1993
- [8] Gruber, P:M:, Asyptotic estimates for best and stepwise approximation of convex bodies II, Forum Math. 5 (1993) 521–538
- [9] Gruber, P.M., Comparisons of best and random approximation of convex bodies by polytopes, *Rend. Circ. Mat. Palermo (2) Suppl.* 50 (1997) 189 – 216
- [10] Gruber, P.M., A short analytic proof of Fejes Tóth's theorem on sums of moments, Aequationes Math. 58 (1999) 291–295
- [11] Gruber, P.M., Optimal configurations of finite sets in Riemannian 2-manifolds, Geom. Dedicata, in print
- [12] Gruber, P.M., in preparation
- [13] Leichtweiss, K., Convexity and differential geometry, in: P.M.Gruber, J.M.Wills, eds., Handbook of convex geometry, vol. B, 1045–1080, North–Holland, Amsterdam 1993
- [14] Ludwig, M., Asymptotic approximation of convex curves, Arch. Math. 63 (1994) 377–384
- [15] Schneider, R., Zur optimalen Approximation konvexer Hyperflächen durch Polyeder, Math. Ann. 256 (1981) 289–301
- [16] Schneider, R., Convex bodies: the Brunn-Minkowski theory, Cambridge University Press, Cambridge 1993
- [17] Tabachnikov, S. On the dual billiard problem, Adv. Math. 115 (1995) 221-249
- [18] Thompson, A.C., Minkowski geometry, Cambridge University Press, Cambridge 1996

P. M. Gruber Abteilung für Analysis Technische Universität Wien Wiedner Hauptstraße 8–10/1142 A–1040 Vienna, Austria peter.gruber+e1142@tuwien.ac.at